



SHADOW DIAGRAM CERTIFICATION

NUMBER: SDC219501
DATE: 10.01.25
PROJECT: 23 Park Ave
 Avalon Beach
 NSW
CLIENT: - Sobi Slingsby Architect
 Lovett Bay NSW

CERTIFICATION FOR :			
DA <input checked="" type="checkbox"/> DA council application	L&E <input type="checkbox"/> All Other Planning Documentation	EXPERT <input type="checkbox"/> Expert Witness Statement	CONSULTANT Primary <input checked="" type="checkbox"/> Other <input type="checkbox"/>
DOCUMENT CONTENTS:			
CERTIFICATE <input checked="" type="checkbox"/> This Page	Statement <input type="checkbox"/> ITEM 2	Process <input checked="" type="checkbox"/> ITEM 3	

I hereby certify that the shadow diagrams provided for this proposed design are accurate and in accordance with the following information.
 This certification is applicable only to the shadow diagrams produced as listed below.

CERTIFICATION DETAILS FOR SHADOW DIAGRAMS		
Project Details	23 Park Ave Avalon Beach . As detailed in DA Plans provided by Sobi Slingsby Architect ,Sobi Slingsby Architect , Dec Issue files	
Applicable for Shadow Diagrams Numbered	SD 01 +	
Issue	Version 01	
Dated	10.01.2025	
ACCURACY DETAILS	DATA	TOLERANCE
Existing Building	Detail Surveys	+/- 150mm Replication of Survey data.
Neighbouring Buildings		
Topography and Site		
Proposed Design	Architectural Plans	+/- 150mm
RL critical heights	Architectural Plans & Survey	+/- 40mm
Shadow Cast per Component	3D Modelling Software (post June 2020 - Vray engine) (pre June 2020 - Mental Ray Engine)	+/- 120mm
Comparative Shadow Analysis per time	3D Model & Post Processing	3 - 5% tolerance across total image frame
PRECEDENCE RULE - DATA		
1. Survey 2. Architectural Plans 3. Aerial Photography		

CERTIFIER SIGNED:

Cameron McFadzean

Certifier:
 Cameron McFadzean
 Registered Architect NSW 8750, BA (Architecture) B Architecture, AssessorABSA, AssocIES
 Deneb Design

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ITEM 1 and 2 not required

ITEM 3. PROCESS OF SHADOW DIAGRAM PRODUCTION – post June 2020 issue

A brief summation of the process of digital shadow production used by Deneb Design follows.

1. 3D Model created from information in typical order of precedence: (refer to specific documents for variation to this order of precedence).
 - 1.1 Survey Plan –
 - 1.2 Architectural Models (3D) and Elevations
 - 1.3 Architectural Plans
 - 1.4 Site Photos / Aerial images.

The accuracy of the translation of these data sources are provided in the certification document. Where accuracy and validity cannot be determined the tolerances are not stated. The tolerances stated are median figures gathered from self auditing process. It is not uncommon for different data sources to contain discrepancies, hence the precedence rule.

2. Sunlight System

Daylight system – a photometrical physically-based light source, based on IES standards (Illuminating Engineering Society) is positioned within the model using True North orientation (derived from Plans/Survey). Date and Time values are set, and these are processed internally by computer algorithms (MAX) to determine azimuth and altitude. The altitude and azimuth angles are available upon request. Pre June 2020 – Mental Ray raytracing engine is used. Post June 2020 – Vray Brute Force ray tracing engine is used.

3. Shadow Image

For each and every time slot a image is rendered using the 3D model and daylight system for every component of the shadow set. A single time slot may consist of several (typically 4) shadow types. Due to render resolution and edge blurriness, particularly in low light where the shadow cast becomes difficult to differentiate accuracy tolerance is determined as a percentage across the entire image. This is as low as 0.5%, however due to the number of passes and composition of the final shadow image this tolerance is indicated as a higher figure and shown in the certification document. Refer also to dynamic range and thresholds for more information. Typical image slots:

- 3.1 Neighboring structures and ground / terrain and other features.
- 3.2 Neighboring shadows cast
- 3.2 Existing Building (if present) and existing shadow cast
- 3.3 Proposed Building and proposed shadow cast
- 3.4 Other Stages or variations if required.

4. Composition

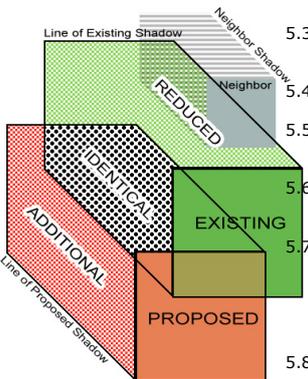
Composition is the ordering and opacity of the image slots. The rendered image slots are compositioned and coloured/separated to create a shadow diagram showing different shadowing of elements – self, existing, proposed, additional etc. This process is subject to human compositioning error only – ie it is either accurate or has an obvious error related to composition – Deneb Design work procedures determine a sequence of steps which has reduced this compositional error to nearly zero occurrence. This composition can include numerous options as per the clients direction.

Algorithms are used to analyse the pixels of each render to determine shadow cast – refer to item 7. Scripts are used to automate the procedure of taking three common shadows – proposed, existing and neighbor, and translating these into more meaningful Reduced, Identical and Additional.

5. Shadow Types – Classifications

A typical shadow diagram has several different shadow types shown. Not all shadow diagrams have all of these types.

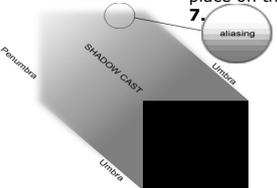
- 5.1 Existing Building and Shadow– The existing building is 3D modeled and the shadow that is cast is called the existing shadow. This existing shadow may also be divided into IDENTICAL and REDUCED Shadow types.
- 5.2 Proposed Building (Orange) and Shadow– The proposed building is modeled and typically shown in PLAN. The shadow cast from this proposed building is called the proposed shadow. This is typically not show by itself – and is divided into IDENTICAL and ADDITIONAL shadow types.
- 5.3 REDUCED Shadow (Green Dot) – The reduced shadow is determined by comparing the existing shadow and the proposed shadow. The proposed shadow is removed from the existing shadow, with any remaining existing shadow now called the reduced shadow. (function is: Existing – Proposed = Reduced Shadow)
- 5.4 IDENTICAL Shadow (Black Dot) - This is the shadow where the existing and proposed shadows coincide – ie they are both the same. (function is: Proposed = Existing)
- 5.5 ADDITIONAL Shadow – (Red Dot) - the additional shadow is determined by comparing the existing shadow and the proposed shadow. The existing shadow is removed from the proposed shadow, with any remaining proposed shadow now called the Additional Shadow. (function is: Proposed – Existing = Additional Shadow)
- 5.6 Neighbor Buildings – Where these are 3D all shadows will be cast across the 3D building. This is important where the shadow casts across a terrain and then travels up the wall. This will show the shadow terminating at the wall in PLAN. If sufficient shadow cast extends over the top of the wall then it will be shown on the roof (and be visible in PLAN).
- 5.7 NEIGHBOR Shadows (grey stripe)– these are shadows cast from neighbor buildings. For clarity of comparison these are shown in combination with all other shadows. Ie We show the existing &/or proposed shadow falling over the top of the neighbor shadow. This is important when considering solar access. Ie the neighbor shadow does not remove the overshadowing of either existing or proposed. This methodology has been brought about by the established “tradition” of not showing any neighbor shadows, and by the complication that not all neighbor buildings can be modeled if they are not on survey.
- 5.8 The methodology of classifying structures into existing, proposed is clearly defined by the architectural plans depicting the proposed works and existing conditions. Typically the survey is used for the existing conditions. The methodology of classifying structures into the neighbor category has some scope which is typically documented and detailed in the plans themselves. Generally most items not within the site boundary are treated as neighbor structures. Existing fences are typically treated as neighbor structures.



6. Layout

Each image time slot in composition becomes a single shadow image. These shadow images are positioned in page with time stamps and titles placed alongside. Deneb Design work procedure has a code checking system to assist in ensuring the correct shadow image is placed in the correct place on the page. This procedure is semi-automated and human error can occur. Self auditing has revealed a <1% occurrence.

7. Shadow Parts and edge accuracy.



The daylight system used in the production of the shadows produces photo-real shadows that have a Umbra (dark part) and a Penumbra (gradient from dark to light). This is most obvious in low sun angles, where the shadows are long. As the length of the shadow increases the edge of it becomes “blurry”. An algorithm analysis each render for the dynamic range to determine where to classify the shadow – ie it determines a threshold value for the greyscale shadow cast. The notion of dynamic range is important to this algorithm for instance in low light (low sun and terrain sloping away from the light) the dynamic range (difference between black and white) in the render is small – thereby reducing the ability to accurately classify the shadow cast. Pre June2020 – Mental Ray raytracing engine . Post June 2020 – Vray brute force engine – which enables more control of these elements for sharper edge definition when required.

8. Solar Calculations

8.1 Methodology and accuracy - Where provided the solar calculations provide numerical areas to various shadow areas – ie existing and proposed. Reference to the definitions in this document is required. The areas are calculated by an algorithm analyzing the shadow area (refer to item 7) and returning a pixel count. This pixel count is then scaled to appropriate unit conversion (typically m2). Due to the item 7 consideration and the scaling effect a tolerance expressed as a % of total image is given. A manual system of translating the area values into a presentation table is used and subject to human error. Several formulas are used within the table to express comparative analysis (% change etc) and these are also subject to human error.

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